

## Amendments to the Claims

As a result of the applicant's election of the claims of Group I, the status of the claims is as follows:

1           1. (Original) A method for measuring the position of an actuator, which has a  
2 coil that moves relative to a core of a magnet, comprising the following steps:  
3           generating an alternating-current (AC) signal through the coil;  
4           sensing current flow through the coil as a coil current signal;  
5           generating a control signal as a function of the coil current signal and having a  
6 frequency corresponding to a position of the coil relative to the core;  
7           generating the AC signal with the same frequency as the control signal; and  
8           as a function of the frequency of the control signal, generating an output position  
9 signal indicating the position of the coil.

1           2. (Original) A method as in claim 1, further including the following steps:  
2           generating a regulator output signal as a function of the difference between an  
3 input position set-point signal and the output position signal; and  
4           generating the control signal as a function of the difference between the regulator  
5 output signal and the coil current signal.

1           3. (Original) A method as in claim 2, in which the step of generating the control  
2 signal comprises applying hysteresis to the regulator output signal before forming the  
3 difference between the regulator output signal and the coil current signal.

1           4. (Original) A method as in claim 1, further comprising the following steps:  
2           measuring a temperature-induced change of resistivity of the coil;  
3           calculating a temperature compensation factor; and  
4           adjusting the control signal by the compensation factor.

1           5. (Original) A method as in claim 4, in which the step of measuring the  
2 temperature-induced change comprises measuring the temperature of the coil.

1           6. (Original) A method as in claim 4, in which the following steps:  
2           measuring the temperature-induced change comprises measuring an average  
3 value of voltage over the coil and an average value of current through the coil; and  
4           calculating the compensation factor as a predetermined function of the ratio  
5 between the average value of voltage and the average value of current.

7. (Canceled)

8. (Canceled)

9. (Canceled)

10. (Canceled)

1           11. (Original) An arrangement for measuring the position of a voice-coil  
2 actuator, comprising:  
3           a permanent magnet core;  
4           a coil arranged to move relative to the core;  
5           an oscillation circuit having, as a first input, an alternating-current (AC) signal  
6 corresponding to an instantaneous current flowing through the coil and having, as an  
7 output, a measurement output signal that has a frequency corresponding to the position  
8 of the coil relative to the core; and  
9           a converter converting the frequency of the measurement output signal into a  
10 position output signal indicating the corresponding to the position of the coil relative to  
11 the core.

12. (Original) An arrangement as in claim 11, further comprising:  
means for measuring a temperature-induced change of resistivity of the coil;  
means for calculating a temperature compensation factor; and  
means for adjusting the control signal by the compensation factor.

13. (Currently amended) An arrangement as in claim 12, in which:  
the means for measuring a temperature-induced change comprises means for  
determining an average value of voltage over the coil and an average value of current  
through the coil; and  
the means for calculating a temperature compensation factor comprises means  
for calculating the compensation factor as a predetermined function of the ratio between  
the average value of voltage and the average value of current.

14. (Original) An arrangement as in claim 11, further comprising:  
a regulator having, as a first input, a position set-point signal corresponding to a  
desired position of the coil; as a second input, the position output signal; and, as an  
output, a position difference signal;  
a comparator having as a first input, the alternating-current (AC) signal; and, as  
an output, the measurement output signal;  
a hysteresis arrangement connected between the output of the regulator and a  
second input of the comparator; and  
a switching arrangement applying current of alternating polarity to the coil at a  
frequency equal to the frequency of the measurement output signal.